

A Connection on M is a bilinear map

$$\begin{aligned} \{\text{vector fields}\} \times \{\text{vector fields}\} &\longrightarrow \{\text{vector fields}\} \\ (X, Y) &\longrightarrow \nabla_X Y \end{aligned}$$

$$\text{st } \nabla_{fX} Y = f (\nabla_X Y)$$

$$\nabla_X fY = f (\nabla_X Y) + (Xf)Y$$

Locally ∇ is determined by

$$\nabla_{\frac{\partial}{\partial x^i}} \frac{\partial}{\partial x^j} = \sum_k \Gamma_{ij}^k \frac{\partial}{\partial x^k} \quad \leftarrow \text{Christoffel symbols of } \nabla.$$

Ex \mathbb{R}^2 The standard ($\Gamma_{ij}^k=0$) connection on \mathbb{R}^n

$$\nabla_{\frac{\partial}{\partial x^i}} Y = \sum_j \frac{\partial Y^j}{\partial x^i} \frac{\partial}{\partial x^j}$$

Hint ANY collection of n^3 functions Γ_{ij}^k determines a connection on \mathbb{R}^n .

Recall: We also have lots of metrics on M .

These two choices can be made in concert.

Thm For every metric g on M $\exists!$ connection ∇ with the following additional properties

$$a) \nabla_X Y - \nabla_Y X = [X, Y] \quad (\text{Torsion Free})$$

$$b) X(g(Y, Z)) = g(\nabla_X Y, Z) + g(Y, \nabla_X Z)$$

∇ is compatible with g .

(∇ encodes g -Leibnitz Rule)

This unique ∇ corresponding to g is called its Riemannian connection.

In local coordinates $g(x) = \sum_{ij} g_{ij}(x) dx^i \otimes dx^j$

$$\text{and } \Gamma_{ij}^k = \frac{1}{2} \sum_{\alpha} g^{\alpha\beta} \left(\frac{\partial g_{\alpha i}}{\partial x^j} + \frac{\partial g_{\alpha j}}{\partial x^i} - \frac{\partial g_{ij}}{\partial x^{\alpha}} \right)$$

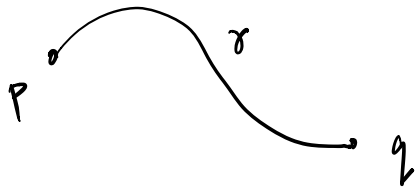
$$\text{where } (g_{ij})^{-1} = (g^{ij})$$

OK, what can we do with ∇ and why is it called a connection?

Parallel Translation

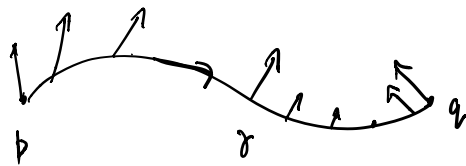
Given $p, q \in M$, want a isomorphism from $T_p M$ to $T_q M$

Let $\gamma: [0, 1] \rightarrow M$ be smooth s.t. $\gamma(0) = p$, $\gamma(1) = q$.



A vector field along γ is a map $V: [0, 1] \rightarrow TM$.

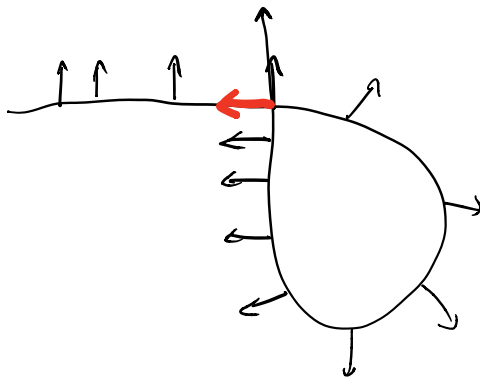
s.t. $V(t) \in T_{\gamma(t)} M$



ex1 $\dot{\gamma}(0)$ is a v.f. along γ .

ex2 A vector field X on M determines one along γ , $X(\gamma(t))$.

ex3



Not every v.f. along γ is a restriction as in ex 2!

A connection ∇ on M defines a unique map.

$$\begin{aligned} \{ \text{Vector fields along } \gamma \} &\longrightarrow \{ \text{Vector fields along } \gamma \} \\ V &\longmapsto \nabla_{\dot{\gamma}} V \end{aligned}$$

s.t. a) $\nabla_{\dot{\gamma}} (V+W) = \nabla_{\dot{\gamma}} V + \nabla_{\dot{\gamma}} W$

b) $\nabla_{\dot{\gamma}} (fV) = f \nabla_{\dot{\gamma}} V + \frac{df}{dt} V$

c) If $V = X(\gamma(t))$ then $\nabla_{\dot{\gamma}} V = \nabla_{\dot{\gamma}} X$.

In local coordinates $V(t) = v^1(t) \frac{\partial}{\partial x^1} + \dots + v^n(t) \frac{\partial}{\partial x^n}$

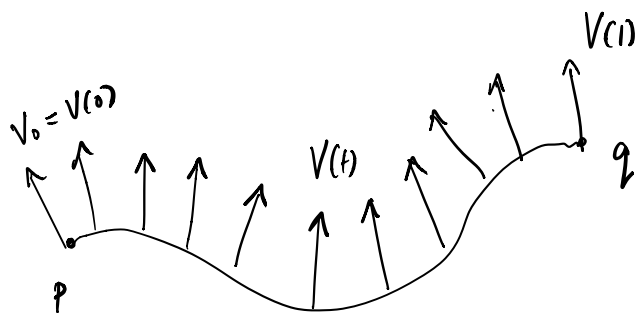
and $(\nabla_{\dot{\gamma}} V)(t) = \sum_k \left(\dot{v}^k(t) + \sum_{i,j} \Gamma_{ij}^k \dot{\gamma}^i(t) v^j(t) \right) \frac{\partial}{\partial x^k}$

Defⁿ A v.f. V along γ is parallel if $\nabla_{\dot{\gamma}} V = 0$.

Thm Given $\gamma: [0,1] \rightarrow M$ smooth at $V_0 \in T(\gamma(0))$

there is a unique parallel v.f. V along γ s.t.

$$V(0) = V_0$$



PF Apply Existence and Uniqueness Thm to

$$\dot{v}^k(t) + \sum_{i,j} \Gamma_{ij}^k(\gamma(t)) \dot{\gamma}^i(t) v^j(t) = 0$$

This are linear equation first order ODE's.

Thm The map $T_p M \rightarrow T_q M$ is an isomorphism!

$$V_0 \mapsto V(1)$$

(It depends on ∇).

Hence "connection"

Fix a metric g on M . Let ∇ be the unique Riemannian connection for g .

Definition $\gamma: (a, b) \rightarrow M$ is a geodesic for g if $\nabla_{\dot{\gamma}} \dot{\gamma} = 0$ ("acceleration" = 0)

In local coordinates

$$\nabla_{\dot{\gamma}} \dot{\gamma} = 0$$

$$\Leftrightarrow \sum_k \left(\ddot{\gamma}^k + \sum_{ij} \Gamma_{ji}^k \dot{\gamma}^i \dot{\gamma}^j \right) \frac{\partial}{\partial x^k} = 0$$

$$\Leftrightarrow \ddot{\gamma}^k + \sum_{ij} \Gamma_{ji}^k \dot{\gamma}^i \dot{\gamma}^j = 0$$

• n 2^{nd} order ODE's

• nonlinear ($\dot{\gamma}^i \dot{\gamma}^j$)

$$\bullet \Gamma_{ij}^k = \frac{1}{2} \sum_l g^{kl} \left(\frac{\partial g_{li}}{\partial x^j} + \frac{\partial g_{lj}}{\partial x^i} - \frac{\partial g_{ij}}{\partial x^l} \right)$$

Example 0 $M = \mathbb{R}^n$ $g_0 = \sum_i dx^i \otimes dx^i$

$$(g_{ij}) = I_n = (g^{ij})$$

$$\Gamma_{ij}^k = 0 \quad \forall i, j, k.$$

The Riemannian connection for g_0 is

$$\nabla_{\frac{\partial}{\partial x^i}} Y = \sum_j \frac{\partial Y^j}{\partial x^i} \frac{\partial}{\partial x^j}$$

The geodesic equations for g_0 are.

$$\ddot{\gamma}^k = 0$$

$$\Rightarrow \dot{\gamma}^k(t) = \dot{\gamma}^k(0) + \ddot{\gamma}^k(0) t$$

$$= \gamma(t) = \gamma(0) + \dot{\gamma}(0) t \quad \text{a straight line.}$$

