

Integrating differential forms

Step 0 $U = [0, 1]^n \subset \mathbb{R}^n$

$$\alpha = f(x) dx^1 \wedge \dots \wedge dx^n$$

$$\int_U \alpha = \int_0^1 \dots \int_0^1 f(x^1, \dots, x^n) dx^1 \dots dx^n.$$

A) Pullback. $F: M \longrightarrow N$

$$\alpha \in \Lambda^k(N)$$

$$\Lambda^k(M) \ni (F^* \alpha)_p(V_1, \dots, V_k) = \alpha(F(p))(F_* V_1, \dots, F_* V_k)$$

Ex $F: \mathbb{R}^2 \longrightarrow \mathbb{R}^3$

$$(x^1, x^2) \longmapsto (x^1 - x^2, x^2 - x^1, (x^1)^2)$$

$$\alpha(y) = \sqrt{y^1} dy^1 \wedge dy^3 \in \Lambda^2(\mathbb{R}^3)$$

$$(F^* \alpha)(x) = \sqrt{x^1 - x^2} d(x^1 - x^2) \wedge d((x^1)^2)$$

$$= \sqrt{x^1 - x^2} \left[(dx^1 - dx^2) \wedge (3(x^1)^2 dx^1) \right]$$

$$= -\sqrt{x^1 - x^2} 3(x^1)^2 dx^2 \wedge dx^1$$

$$= \sqrt{x^1 - x^2} \sum (x^i)^2 dx^1 \wedge dx^2.$$

Ex $\gamma: (a, b) \longrightarrow \mathbb{R}^n$
 $t \longmapsto (\gamma_1(t), \dots, \gamma_n(t))$

$$\alpha(x) = \sum a_i(x) dx^i$$

$$\begin{aligned} (\gamma^* \alpha)(t) &= \sum_i a_i(\gamma(t)) d(\gamma_i(t)) \\ &= \sum_i a_i(\gamma(t)) \frac{d\gamma_i}{dt}(t) dt \\ &= \left[\sum_i a_i(\gamma(t)) dx^i \right] \left(\sum \frac{d\gamma_j}{dt}(t) \frac{\partial \gamma_j}{\partial x^i} \right) dt. \\ &= \alpha(\gamma(t)) (\dot{\gamma}(t)) dt. \end{aligned}$$

$$\int_{\gamma} \alpha = \int_a^b \alpha(\gamma(t)) (\dot{\gamma}(t)) dt = \int_a^b \gamma^* \alpha$$

Step 1 Given $\omega \in \Lambda^k(M)$ and a smooth map

$$\gamma: [0, 1]^k \rightarrow M \quad (\text{singular } k\text{-cube})$$

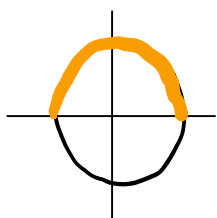
$$\int_{\gamma} \omega = \int_{[0, 1]^k} \gamma^* \omega \quad \leftarrow \text{as defined in Step 0.}$$

Now suppose $U \subset M$ and $U = \gamma([0,1]^n)$ for some $\gamma: [0,1]^n \rightarrow M$ which is smooth and 1-1.

Q. Does it make sense to define $\int_U \omega = \int_{\gamma} \omega$?

A. NO. There is a sign problem.

Example $M = S^1$ $U = \{x \in S^1 \mid x^2 \geq 0\}$



$$\begin{aligned} \gamma_1 : [0,1] &\rightarrow S^1 \\ t &\mapsto (\cos(\pi t), \sin(\pi t)) \end{aligned}$$

$$\begin{aligned} \gamma_2 : [0,1] &\rightarrow S^1 \\ s &\mapsto (\cos(\pi(1-s)), \sin(\pi(1-s))) \end{aligned}$$

$$\gamma_1([0,1]) = U = \gamma_2([0,1])$$

Exercise: For any 1-form α on S^1 $\int_{\gamma_1} \alpha = -\int_{\gamma_2} \alpha$.

We need a way to consistently choose basis signs.

B) Orientations

Let $\alpha = \{e_1, \dots, e_n\}$ and $\beta = \{f_1, \dots, f_n\}$ be basis for V .

$[\text{Id}_V]_{\alpha}^{\beta}$ is an invertible matrix. $\left(\left([\text{Id}_V]_{\alpha}^{\beta}\right)^{-1} = [\text{Id}_V]_{\beta}^{\alpha}\right)$

Def² $\alpha \sim \beta$ iff $\det([\text{Id}_V]_{\alpha}^{\beta}) > 0$

Ex $V = \mathbb{R}^2$

$\alpha = \{(1,0), (0,1)\}$

$\beta = \{(0,1), (1,0)\}$

$\gamma = \{(1,1), (1,-1)\}$

$$[\text{Id}]_{\alpha}^{\beta} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad \text{s.t.} \quad \alpha \not\sim \beta.$$

$$[\text{Id}]_{\alpha}^{\gamma} = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} \end{pmatrix} \quad \text{s.t.} \quad \alpha \not\sim \gamma$$

$$[\text{Id}]_{\beta}^{\gamma} = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{pmatrix} \quad \text{s.t.} \quad \beta \sim \gamma$$

Fact For any V there are exactly 2 equivalence classes of bases $\{+, -\}$

Defⁿ An orientation of V is a choice of one equivalence class of bases $(+)$.

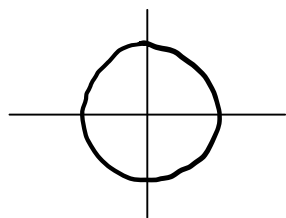
Let (U, ϕ) and (V, ψ) be charts on M .

Defⁿ (U, ϕ) and (V, ψ) are orientation compatible if either $U \cap V = \emptyset$ or if.

$$\det \left(\begin{array}{c} \left[(\psi \circ \phi^{-1})_* \right]_{\substack{\{ \frac{\partial}{\partial y^j} \} \\ y \\ \{ \frac{\partial}{\partial x^i} \} \\ x}} \end{array} \right) > 0$$

for all $x \in \phi(U \cap V)$

Ex $M = S^1$ (U_1^+, ϕ_1^+) (U_2^+, ϕ_2^+)



$$\begin{aligned}\phi_2^+ \circ (\phi_1^+)^{-1}(x^1) &= \phi_2^+(\sqrt{1-(x^1)^2}, x^1) \\ &= \sqrt{1-(x^1)^2}\end{aligned}$$

$$\begin{aligned}\left[(\phi_2^+ \circ (\phi_1^+)^{-1})_* \right] &= \frac{\partial}{\partial x^1} (\sqrt{1-(x^1)^2}) \\ &= \frac{-x^1}{\sqrt{1-(x^1)^2}} < 0\end{aligned}$$

So not orientation compatible.

Ex Change ϕ_2^+ to $\hat{\phi}_2^+(x^1, x^2) = -x^1$.

Then (U_1^+, ϕ_1^+) and $(U_2^+, \hat{\phi}_2^+)$ are orientation compatible.

Def³ M is orientable if it admits an atlas

$\mathcal{A} = \{ (U_\alpha, \phi_\alpha) \}_{\alpha \in I}$ such that any two charts in \mathcal{A} are orientation compatible.

Such an atlas is said to be orienting.

Remark Not all manifolds are orientable!

ex $\mathbb{R}P^2$ is not orientable

Def² Let \mathcal{A} and \mathcal{B} be orienting atlases for M .

$\mathcal{A} \sim \mathcal{B}$ if every pair of charts $(U, \phi) \in \mathcal{A}$
and $(V, \psi) \in \mathcal{B}$ are orientation compatible.

Fact If M is orientable it has exactly two equivalence classes of orienting atlases.

Def³ An orientation on an orientable manifold is a choice of one of these equivalence classes.

Def³ M oriented. (U, ϕ) is positively oriented if it belongs to an oriented atlas in the chosen equivalence class.

Ex $M = \mathbb{R}^n$

$\mathcal{A} = \{(\mathbb{R}^n, \text{Id}_{\mathbb{R}^n})\}$ is an orienting atlas.

$\mathcal{B} = \{(\mathbb{R}^n, -\text{Id}_{\mathbb{R}^n})\}$ is an orienting atlas

$\mathcal{A} \sim \mathcal{B} \iff n$ is even

i.e. $\det \left[(-\text{Id}_{\mathbb{R}^n}) \cdot (\text{Id}_{\mathbb{R}^n})^{-1} \right] = \det(-\mathbb{I}_n) = (-1)^n.$

Def² Suppose M is oriented. $\gamma: [0, 1]^n \rightarrow M$ is positively oriented if $\det [(\phi \circ \gamma)_*]$ for any positively oriented chart on (U, ϕ) on M (with $U \cap \gamma([0, 1]^n) \neq \emptyset$).