

Riemannian metrics as measuring tools.

Let  $g$  be a Riemannian metric on  $M$

$$\begin{aligned} \|\cdot\|_g : T_p M &\longrightarrow \mathbb{R} \\ V &\longmapsto \sqrt{g(p)(V, V)} \end{aligned}$$

Let  $\gamma: [a, b] \rightarrow M$  be a smooth curve.

$$L_g(\gamma) = \int_a^b \|\dot{\gamma}(t)\|_g dt.$$

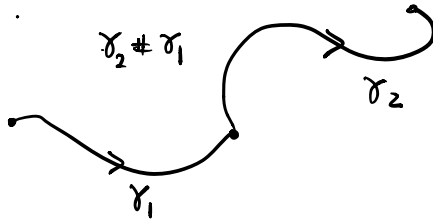
Def<sup>D</sup>  $\gamma$  is regular if  $\dot{\gamma}(t) \neq \bar{0} \in T_{\gamma(t)} M$   
for all  $t \in [a, b]$ .

Fact If two regular curves  $\gamma, \tilde{\gamma}$  have the  
same image then  $L_g(\gamma) = L_g(\tilde{\gamma})$ .

Def<sup>A</sup>  $\gamma: [a, b] \rightarrow M$  is piecewise smooth if it is continuous  
and there are numbers  $a < t_1 < t_2 < \dots < t_k < b$  such that  
 $\gamma$  is smooth on the domains  $(a, t_1), (t_1, t_2), \dots, (t_k, b)$ .

ex If  $\gamma_1, \gamma_2: [0, 1] \rightarrow M$  are smooth and  $\gamma_1(1) = \gamma_2(0)$   
then their concatenation is the piecewise smooth curve

$$\gamma_2 \# \gamma_1 = \begin{cases} \gamma_1(2t) & t \in [0, 1/2] \\ \gamma_2(2t-1) & t \in [1/2, 1] \end{cases}$$



Exercise  $L_g(\gamma)$  makes sense for piecewise smooth curves.

Exercise  $L_g(\gamma_2 \# \gamma_1) = L_g(\gamma_1) + L_g(\gamma_2)$ .

Def<sup>n</sup> The distance between  $p, q \in M$  (w.r.t.  $g$ ) is

$$d_g(p, q) = \infimum \{ L_g(\gamma) \}$$

$\gamma: [0, 1] \rightarrow M$   
 $\gamma$  piecewise smooth  
 $\gamma(0) = p, \gamma(1) = q$

Could restrict to regular curves, same number.

Recall

$\infimum \{ S \} =$  greatest lower bound. of  $S$

ex  $\infimum \{ \frac{1}{n} \mid n \in \mathbb{N} \} = 0 \notin \{ \frac{1}{n} \mid n \in \mathbb{N} \}$ .

facts:  $S_1 \subset S_2 \Rightarrow \infimum S_1 \geq \infimum S_2$

$\infimum(S_1 + S_2) = \infimum S_1 + \infimum S_2$ .

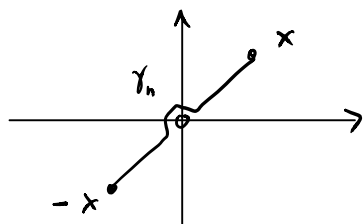
Example 0  $M = \mathbb{R}^n$   $g = \sum_{i=1}^n dx^i \otimes dx^i$

$d_g(x, y) = \|y - x\| = L_g(t \mapsto x + (1-t)y)$

Example 1  $M = \mathbb{R}^n \setminus \{0\}$   $g = \sum_{i=1}^n dx^i \otimes dx^i$

$d_g(x, -x) = \|x + x\| = 2\|x\|$

$\neq L_g(\gamma)$  for any  $\gamma$  in  $M$  from  $x$  to  $-x$



Thm 1)  $d_g(p, q) = d_g(q, p)$

2)  $d_g(p, r) \leq d_g(p, q) + d_g(q, r)$

3)  $d_g(p, q) > 0$  if  $p \neq q$ .

Pf

1)

Observation 1:

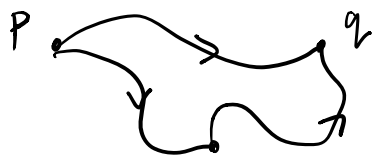
$$\begin{array}{ccc}
 \gamma : [0,1] \rightarrow M & \xrightarrow{\gamma(t) \mapsto \gamma(1-t)} & \eta : [0,1] \rightarrow M \\
 \gamma(0) = p, \gamma(1) = q & & \eta(0) = q, \eta(1) = p \\
 & \xleftarrow{\eta(1-t) \leftarrow \eta(t)} & 
 \end{array}$$

Observation 2 :  $L_g(\gamma(t)) = L_g(\gamma(1-t))$

$$\begin{aligned}
 d_g(p, q) &= \inf_{\gamma} \{L_g(\gamma)\} \\
 &\quad \begin{array}{c} \curvearrowright \\ p \rightarrow q \end{array} \\
 &= \inf_{\eta} \{L_g(\eta)\} \quad (\text{since same set of numbers}) \\
 &\quad \begin{array}{c} \curvearrowleft \\ q \rightarrow p \end{array} \\
 &= d_g(q, p)
 \end{aligned}$$

2)

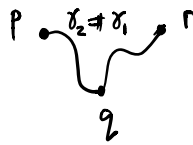
Observation : The set of paths from  $p$  to  $r$  contains the set of concatenated paths from  $p$  to  $r$  with matching ends at  $q$ .



$$d_g(p, r) = \inf_{\gamma} \{ L_g(\gamma) \}$$



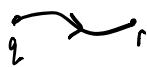
$$\leq \inf_{\gamma_2 \# \gamma_1} \{ L_g(\gamma_2 \# \gamma_1) \}$$



$$= \inf_{\gamma_1} \{ L_g(\gamma_1) + L_g(\gamma_2) \}$$



$\gamma_2$



$$= \inf_{\gamma_1} \{ L_g(\gamma_1) \} + \inf_{\gamma_2} \{ L_g(\gamma_2) \}$$

$$= d_g(p, q) + d_g(q, r)$$

3) Nondegeneracy is a bit more subtle, but crucial

Idea if  $p, q \in U$  for a chart  $(U, \phi)$ , then

$$d_g(p, q) \geq c \|\phi(p) - \phi(q)\| \text{ for some } c(U, \phi).$$

## k-forms.

Def<sup>1</sup> A 0-form on  $M$  is a function  $f \in C^0(M)$ .

Def<sup>2</sup> A 1-form on  $M$  is a covector field  $\alpha: M \rightarrow T^*M$   
( $\pi \circ \alpha = \text{Id}_M$ ).

Def<sup>3</sup> For  $k \geq 2$  a  $k$ -form on  $M$  is a  $(k,0)$ -tensor field

$$\alpha: M \rightarrow \bigoplus_{k,0} (M)$$

$$p \mapsto (p, \alpha(p))$$

such that for all  $q \in M$ , all  $V_1, \dots, V_k \in T_q M$

and all  $i < j$  we have

$$\alpha(p)(V_1, \dots, V_i, \dots, V_j, \dots, V_k) = -\alpha(p)(V_1, \dots, V_j, \dots, V_i, \dots, V_k).$$

Such a tensor is said to be alternating.

- $k$ -forms are the correct objects to integrate over  $k$ -dimensional domains
- the set of  $k$ -forms, over all  $k$ , has a rich algebraic structure which captures a lot of topology.

- to understand  $k$ -forms we must understand what they look like in local coordinates.