

$$\mathcal{T}_{r,s}(M) = \{ (p, W) \mid W \in \mathcal{T}_{r,s}(T_p M) \}$$

A  $(r,s)$ -tensor field on  $M$  is a map  $T: M \rightarrow \mathcal{T}_{r,s}(M)$  such that  $\pi \circ T = \text{Id}_M$ .

$$T(p) = (p, W(p))$$

$\curvearrowright \in \mathcal{T}_{r,s}(T_p M)$ .

In coordinates given by a chart  $(U, \phi)$

$\left\{ \frac{\partial}{\partial x^i} \Big|_p \right\}$  is a basis for  $T_p M$ .

$\left\{ dx^j \Big|_p \right\}$  is the dual basis for  $T_p^* M$

and

$$W(p) = \sum_{\substack{1 \leq k_1, \dots, k_s \leq n \\ 1 \leq t_1, \dots, t_r \leq n}} W_{t_1 \dots t_r}^{k_1 \dots k_s}(p) \frac{\partial}{\partial x^{k_1}} \Big|_p \otimes \dots \otimes \frac{\partial}{\partial x^{k_s}} \Big|_p \otimes dx^{t_1} \Big|_p \otimes \dots \otimes dx^{t_r} \Big|_p$$

We will simplify this notation to

$$W(x) = \sum_{t_1, \dots, t_r} W_{t_1 \dots t_r}^{k_1 \dots k_s}(x) \frac{\partial}{\partial x^{k_1}} \otimes \dots \otimes \frac{\partial}{\partial x^{k_s}} \otimes dx^{t_1} \otimes \dots \otimes dx^{t_r}$$

where  $x = \phi(p)$ .

Rmk given  $f \in C^\infty(M)$  and an  $(r,s)$ -tensor field we can construct another  $(r,s)$ -tensor field  $fW$ .

$$fW \begin{matrix} k_1, \dots, k_s \\ t_1, \dots, t_r \end{matrix} (x) = f(x) W \begin{matrix} k_1, \dots, k_s \\ t_1, \dots, t_r \end{matrix} (x)$$

Rmk given two  $(r,s)$ -tensor fields  $W, \tilde{W}$  their sum  $W + \tilde{W}$  is the  $(r,s)$ -tensor field defined (locally) by

$$(W + \tilde{W}) \begin{matrix} k_1, \dots, k_s \\ t_1, \dots, t_r \end{matrix} (x) = \left( W \begin{matrix} k_1, \dots, k_s \\ t_1, \dots, t_r \end{matrix} (x) + \tilde{W} \begin{matrix} k_1, \dots, k_s \\ t_1, \dots, t_r \end{matrix} (x) \right)$$

Now a new kind of tensor field.

Def<sup>n</sup> A Riemannian metric on  $M$  is a smooth  $(2,0)$ -tensor field  $g : M \rightarrow \mathcal{T}_{(2,0)}(M)$  such that

i)  $g(p)(X, Y) = g(p)(Y, X) \quad \forall X, Y \in T_p M$

( $g$  is symmetric)

ii)  $g(p)(X, X) > 0$  for all  $0 \neq X \in T_p M$

( $g$  is positive definite).

Let's view (i) and (ii) in local coordinates.

In general local coordinates:

$$g(x) = \sum_{1 \leq t_1, t_2 \leq 2} g_{t_1 t_2}(x) dx^{t_1} \otimes dx^{t_2}$$

$$\text{where } g_{t_1 t_2}(x) = g(x) \left( \frac{\partial}{\partial x^{t_1}}, \frac{\partial}{\partial x^{t_2}} \right)$$

$$\text{or } g(x) = \sum_{1 \leq i, j \leq n} g_{ij}(x) dx^i \otimes dx^j$$

$$\text{where } g_{ij}(x) = g(x) \left( \frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j} \right)$$

•  $g$  is locally defined by the  $n \times n$  matrix function  $(g_{ij}(x))$ .

$$g \text{ symmetric} \iff g_{ij}(x) = g_{ji}(x)$$

$$\iff (g_{ij}(x)) = (g_{ij}(x))^T$$

Recall from linear algebra

$$A = A^T \implies \exists B \text{ s.t. } B^T B = I_n \text{ and}$$

$$B^T A B = \begin{pmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{pmatrix}, \lambda_i \in \mathbb{R}$$

$A$  has real eigenvalues and is diagonalizable.

$g$  symmetric and positive definite  $\Leftrightarrow$  all eigenvalues are positive.  
(i) + (ii)

Note  $(g_{ij}(x))$  is invertible!

Example 0  $M = \mathbb{R}^n$   $g(x) = \sum_{i=1}^n dx^i \otimes dx^i$

Here  $(g_{ij}(x)) = \mathbb{I}_n$

This is the standard (Euclidean) metric (dot product) on  $\mathbb{R}^n$ .

Example 1  $M = \{ (x^1, x^2) \in \mathbb{R}^2 \mid x^2 > 0 \} \subset \overset{\text{open}}{\mathbb{R}^2}$

$$g(x) = \frac{1}{(x^2)^2} \sum_{i=1}^2 dx^i \otimes dx^i$$

$$(g_{ij}(x)) = \frac{1}{(x^2)^2} \mathbb{I}_2$$

This is called the hyperbolic (or Poincaré) metric.

## Example 2

Let  $g_{\text{st}}$  be the standard metric on  $\mathbb{R}^n$

Let  $q$  be a regular value of  $F: \mathbb{R}^n \rightarrow \mathbb{R}$

Recall  $T_x(F^{-1}(q)) = N(F_*) \subset T_x \mathbb{R}^n$ .

The restriction of  $g_{\text{st}}$  to  $T_x(F^{-1}(q))$  is a

Riemannian metric on  $F^{-1}(q)$

$$\begin{aligned} \text{ex 2 } F: \mathbb{R}^3 &\longrightarrow \mathbb{R} \\ x &\longmapsto \|x\|^2 \end{aligned}$$

The restriction of  $g_{\text{st}}$  to  $F^{-1}(1) = S^2$  is called the round metric on  $S^2$ .

Example 3 If  $N$  is an embedded submanifold

of  $M$  and  $g$  is a metric on  $M$ , then it

restricts to a metric on  $N$ .

Thm Every manifold  $M$  admits a Riemannian metric.

This is VERY fortunate since metrics are our primary measuring tools.

This is not trivial.  $g$  positive definite  $\Rightarrow g$  is nonvanishing.

Recall:  $S^2$  doesn't admit nonvanishing vector fields.

In fact each manifold admits lots of metrics.

Method 1 given  $g$  and  $f \in C^\infty(M)$  s.t.  $f(p) > 0 \quad \forall p \in M$   
 $fg$  is also a metric

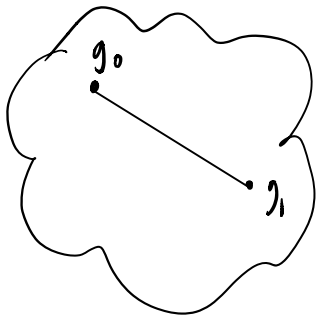
$$(fg)_{ij}(x) = f(x) g_{ij}(x)$$

Method 2 If  $g$  and  $\tilde{g}$  are metrics so is  
 $g + \tilde{g}$ .

PF  $(g + \tilde{g})(X, X) = g(X, X) + \tilde{g}(X, X)$   
 $> 0$  if  $X \neq 0$ .

Example Any two metrics  $g_0$  and  $g_1$  are connected by a straight line of metrics.

$$g_t = (1-t)g_0 + t g_1$$



"The set of metrics in  $\mathcal{T}_{2,0}(M)$  is convex."

Idea behind existence of a metric on  $M$ .

- Given  $(U, \phi)$  define  $g^u$  on  $U$  by

$$(g_{ij}^u(x)) = \mathbb{I}_n.$$

- Given another chart  $(V, \psi)$  with  $U \cap V \neq \emptyset$  define

$$g^v \text{ by } (g_{ij}^v(y)) = \mathbb{I}_n.$$

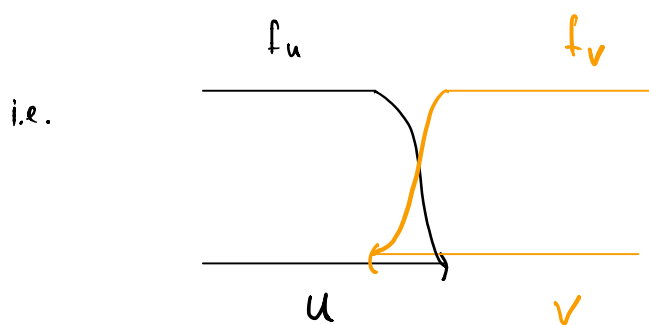
We need to patch these together nicely.

Prop There exist smooth functions  $f_u, f_v: U \cup V \rightarrow \mathbb{R}$

s.t. i)  $f_u(p) \geq 0$  and  $f_u(p) = 0$  if  $p \notin U$

ii)  $f_v(p) \geq 0$  and  $f_v(p) = 0$  if  $p \notin V$

iii)  $(f_u + f_v)(p) = 1 \quad \forall p \in U \cup V.$



Now  $f_u g^u + f_v g^v$  is a metric on  $U \cup V$ .

Continuing in this way we get a  $g$  on  $M$ .

(Use countable base assumption for  $M$  here.)