

Defⁿ (provisional)

A smooth manifold is a set M equipped with a smooth atlas $\mathcal{A} = \{(U_\alpha, \phi_\alpha)\}_{\alpha \in A}$.

Let's deal with the "provisional"

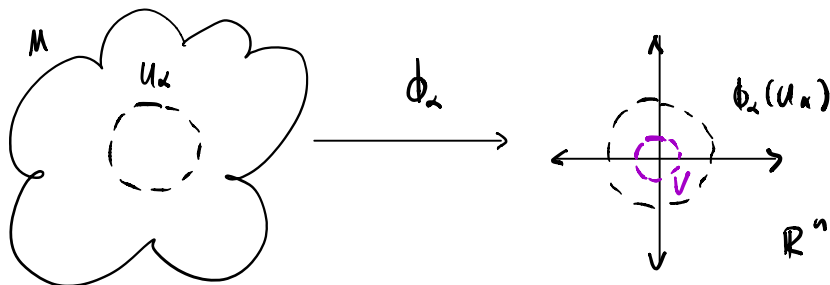
Defⁿ a chart (U, ϕ) is compatible with \mathcal{A} if it is compatible with each $(U_\alpha, \phi_\alpha) \in \mathcal{A}$.

Exercise If (U, ϕ) is compatible with \mathcal{A} , then $\mathcal{A} \cup \{(U, \phi)\}$ is an atlas on M .

Basic Problem It is easy to find (U, ϕ) compatible w \mathcal{A} and we don't want to view (M, \mathcal{A}) and $(M, \mathcal{A} \cup \{(U, \phi)\})$ as different smooth manifolds.

Method 1 Restriction

Choose $(U_\alpha, \phi_\alpha) \in \mathcal{A}$ and $V \subset_{\text{open}} \phi_\alpha(U_\alpha)$



Exercise $(\phi_\alpha^{-1}(V), \phi_\alpha)$ is a chart compatible w/ \mathcal{A} .

Method 2 Composition

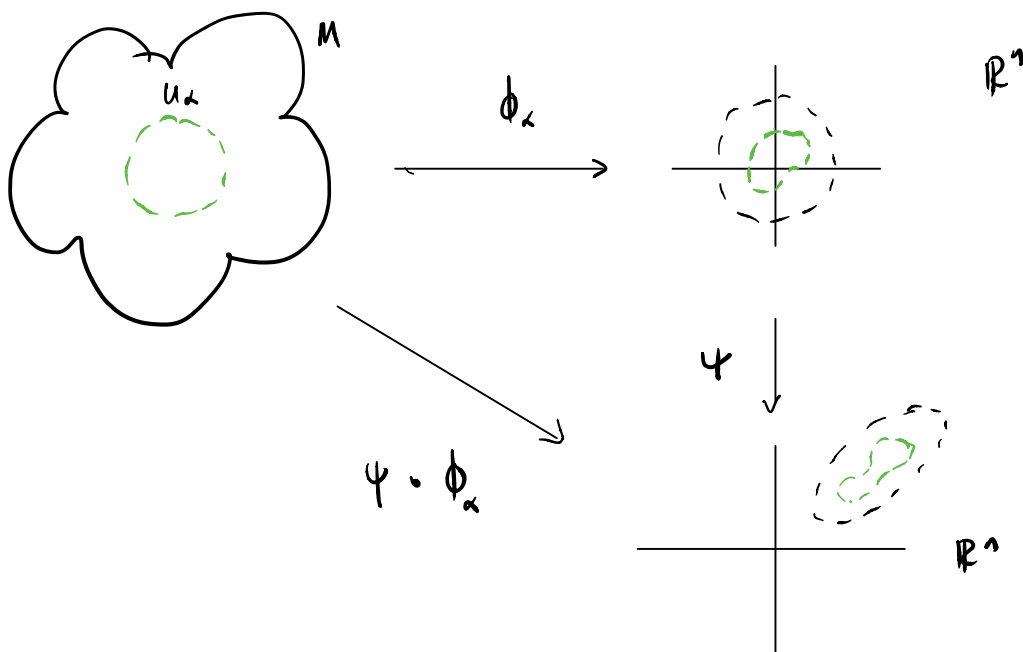
Let $\psi: \mathbb{R}^n \rightarrow \mathbb{R}^n$ be smooth with smooth inverse.

ex If A is an invertible matrix and $c \in \mathbb{R}^n$

the map $\psi(x) = Ax + c$ is smooth as is its

inverse $\psi^{-1}(y) = A^{-1}(y - c)$

Exercise For $(U_\alpha, \phi_\alpha) \in \mathcal{A}$, $(U_\alpha, \psi \circ \phi_\alpha)$ is a chart compatible with \mathcal{A} .



Let's deal with the Basic Problem.

Defⁿ two atlases \mathcal{A} and \mathcal{A}' on M are compatible ($\mathcal{A} \sim \mathcal{A}'$) if each chart of \mathcal{A} is compatible with each chart of \mathcal{A}' .

Defⁿ (?) A smooth manifold is a set M equipped with a equivalence class of smooth atlases, $[\mathcal{A}]$.

Now $(M, [\mathcal{A}]) = (M, [\mathcal{A} \cup \{(\psi, \phi)\}])$

There is still a subtle (topological) problem.

Given an atlas \mathcal{A} for M add to it all charts compatible with \mathcal{A} to get $\max(\mathcal{A})$.

- $\max(\mathcal{A})$ is an atlas on M
- $[\max(\mathcal{A})] \sim [\mathcal{A}]$.
- every chart compatible w/ $\max(\mathcal{A})$ is in $\max(\mathcal{A})$.
- $\mathcal{A} \sim \mathcal{A}' \Leftrightarrow \max(\mathcal{A}) = \max(\mathcal{A}')$.

Topology from an atlas.

Let \mathcal{A} be an atlas on M . $(M, [\mathcal{A}])$ is smooth mfd.

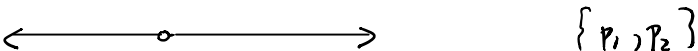
$W \subset M$ is open if for each $p \in W$ there is a $(U, \phi) \in \max(\mathcal{A})$ such that $p \in U \subset W$.

This collection of open sets of M defines a topology on M .

Defⁿ A smooth manifold is a pair $(M, [\mathcal{A}])$ such that the (induced) topology on M is Hausdorff and has a countable base.

Hausdorff: For $p \neq q \in M$ there are open sets $U, V \subset M$ s.t. $p \in U$, $q \in V$ and $U \cap V = \emptyset$.

Example $M = \mathbb{R} \setminus \{0\} \cup \{p_1, p_2\}$



$$U_1 = M \setminus \{p_2\}$$

$$U_2 = M \setminus \{p_1\}$$

$$\phi_1 : U_1 \rightarrow \mathbb{R}$$

$$x \mapsto x$$

$$p_1 \mapsto 0$$

$$\phi_2 : U_2 \rightarrow \mathbb{R}$$

$$x \mapsto x$$

$$p_2 \mapsto 0$$

$\{(U_1, \phi_1), (U_2, \phi_2)\}$ is a smooth atlas on M

The topology on M is not Hausdorff.

Let $(M, [a])$ be a smooth manifold of dimension n .

Let $C^\infty(M) = \{ \text{smooth functions on } M \}$

$C^\infty(M)$ is a vector space. $(f+g)(p) = f(p) + g(p)$

$$(cf)(p) = c(f(p))$$

Let $f: M \rightarrow \mathbb{R}$ be smooth.

Q. What is the derivative of f at $p \in M$?

A. It is a linear map from $T_p M$ to \mathbb{R} .

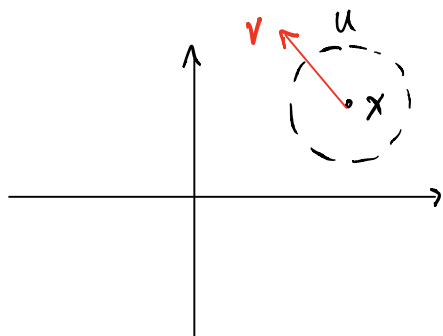
Q. What is $T_p M$?

- By name, $T_p M$ is the tangent space to M at p .
- $T_p M$ is a vector space of dimension n .
- $T_p M$ is a collection of linear maps from $C^\infty(M)$ to \mathbb{R} .
- Each chart (U, ϕ) with $p \in U$ determines a basis for $T_p M$.

Let's look at things in Example 0.

$$M = U \subset \mathbb{R}^n \quad \mathcal{A} = \{ (U, \text{Id}_U) \}$$

open



- A tangent vector to M at x is a vector v w/ base at x
- The space of all such vectors is a copy of \mathbb{R}^n with origin at x . Hence a vector space of dimension n .

• Each v determines a map

$$D_v : C^0(M) \longrightarrow \mathbb{R}$$
$$f \longmapsto \left. \frac{d}{dt} \right|_{t=0} f(x+tv)$$

This map is linear.

$$\begin{aligned} D_v(f+cg) &= \left. \frac{d}{dt} \right|_{t=0} (f+cg)(x+tv) \\ &= \left. \frac{d}{dt} \right|_{t=0} (f(x+tv) + c(g(x+tv))) \\ &= D_v(f) + c D_v(g). \end{aligned}$$

This map satisfies the product rule

$$D_v(fg) = D_v f \cdot g(x) + f(x) D_v g$$

Fact Any linear map satisfying this rule is equal to D_v for some v .

$$S_0 \quad v \leftrightarrow D_v$$

Defⁿ For a smooth manifold $(M, [a])$, the tangent space to M at p is

$$T_p M = \left\{ L: C^\infty(M) \rightarrow \mathbb{R} \mid \begin{array}{l} L \text{ is linear and} \\ L(fg) = L(f)g(p) + f(p)L(g) \end{array} \right\}$$