

Hopf-Rinow theorem

Now we will address whether any two points in a Riemannian manifold can be joined by a shortest path.

Recall the exponential map $\exp: TM \rightarrow M$, and the distance function $\text{dist}_g: M \times M \rightarrow \mathbb{R}$, $\text{dist}_g(p, q) = \inf \left\{ l(\gamma) \mid \begin{array}{l} \gamma(0) = p, \gamma(1) = q \\ \gamma \text{ a piecewise smooth path} \end{array} \right\}$

Def (M, g) is **geodesically complete** if every geodesic can be extended for all time. In other words, the exponential map $\exp_q(v)$ is defined for all $(q, v) \in TM$.

Recall Def (M, d) is **complete as a metric space** if every Cauchy sequence has a limit.

Theorem (Hopf-Rinow) (M, g) is geodesically complete if and only if (M, dist_g) is complete as a metric space. Moreover, if (M, g) is geodesically complete then any two points p, q may be joined by a geodesic whose length equals $\text{dist}_g(p, q)$. (That is, minimizers always exist.)

Proof Part 1: Geodesically complete \Rightarrow minimizers exist.

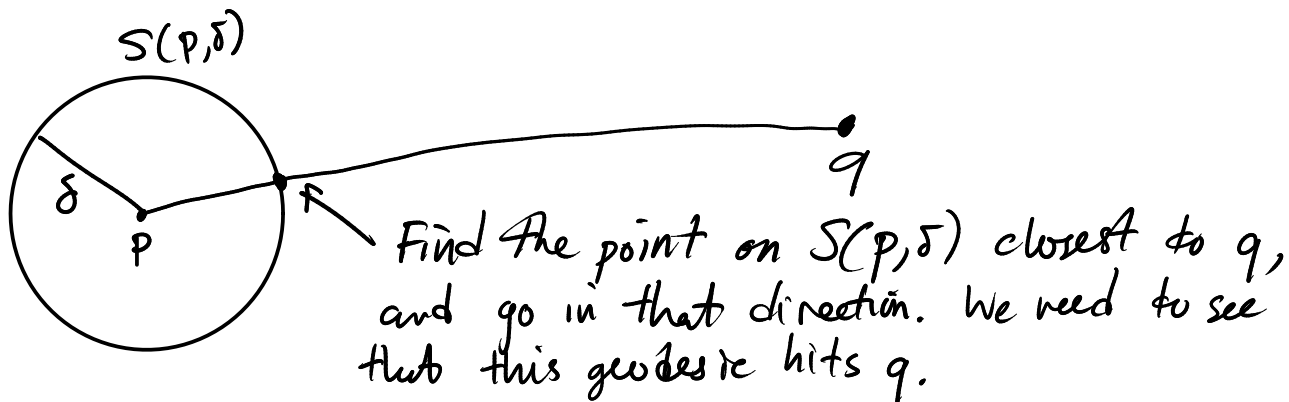
Let $p, q \in M$, and set $r = \text{dist}_g(p, q)$.

Let U_p be an open set around p and $\varepsilon > 0$ such that

$$\exp_p: \{v \in T_p M \mid \|v\| < \varepsilon\} \rightarrow U_p \text{ is a diffeo.}$$

(This exists by results of previous lecture).

Pick $\delta < \varepsilon$, and consider $S = S(p, \delta)$ the spherical shell



More precisely: The function $\text{dist}_g(q, -): S \rightarrow \mathbb{R}$ achieves its minimum at some $p_0 \in S$ (since it is a continuous function on a compact set).

Thus $p_0 = \exp_p(\delta v)$ for $v \in T_p M$ $\|v\| = 1$
and $\text{dist}_g(p_0, q) \leq \text{dist}_g(s, q) \quad \forall s \in S$.

Claim (*): $\exp_p(rv) = q$ (This will complete part 1)

Set $\gamma(t) = \exp_p(tv)$. It exists for all t by geodesic completeness.
The previous claim is a special case of

Claim (**): $\text{dist}(\gamma(t), q) = r - t$ for $t \in [\delta, r]$
(take $t = r$ to get (*))

Proof of (**) for $t = \delta$: Need to show $\text{dist}(p_0, q) = r - \delta$

well

$$r = \text{dist}(p, q) = \inf_{s \in S} (\text{dist}(p, s) + \text{dist}(s, q)) \quad \text{since every path touches } S.$$

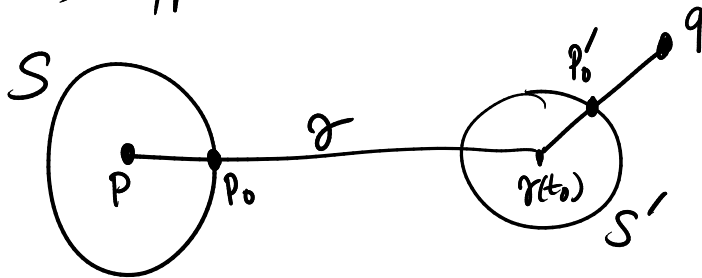
$$= \inf_{s \in S} (\delta + \text{dist}(s, q)) = \delta + \inf_{s \in S} \text{dist}(s, q)$$

$$= \delta + \text{dist}(p_0, q) \quad \text{since } p_0 \text{ is closest point on } S \text{ to } q.$$

Thus $\text{dist}(p_0, q) = r - \delta \quad \checkmark$

Now consider the set I of $t \in [\delta, r]$ for which $(**)$ holds. We know $\delta \in I$, so $I \neq \emptyset$. It is also clear that I is closed, because $(**)$ is equivalent to the vanishing of the continuous function $\text{dist}(\gamma(t), q) - (r-t)$. If we can show that I is also open, we will know that $I = [\delta, r]$, since the only nonempty open and closed subset of a connected space is the whole space itself. [This sort of argument is called the "continuity method".]

For openness, suppose $(**)$ holds for $t = t_0$



Let S' be shell of radius δ' around $\gamma(t_0)$. Let $p'_0 \in S'$ be point on S' closest to q .

Then $\text{dist}(\gamma(t_0), q) = \delta' + \text{dist}(p'_0, q)$ like before

But $\text{dist}(\gamma(t_0), q) = r - t_0$ by assumption.

So

$$\text{dist}(p'_0, q) = r - t_0 - \delta' = r - (t_0 + \delta')$$

By triangle inequality

$$\text{dist}(p, p'_0) \geq \text{dist}(p, q) - \text{dist}(p'_0, q) = r - (r - (t_0 + \delta')) = t_0 + \delta'$$

But the path $p \rightarrow q$ obtained for following γ $p \rightarrow \gamma(t_0)$ and then the radial geodesic $\gamma(t_0) \rightarrow p'_0$ has length $t_0 + \delta'$

It is therefore an absolutely minimal path between its endpoints and so it is a geodesic. Since part of this geodesic coincides with γ , the whole thing coincides with γ .

We find $\gamma(t_0 + \delta') = p_0'$,
 so $\text{dist}(\gamma(t_0 + \delta'), q) = r - (t_0 + \delta')$, so $t_0 + \delta' \in I$.

In summary, we have shown the following facts about $I \subset [\delta, r]$:

- $\delta \in I$, so $I \neq \emptyset$
- I is closed
- If $t_0 \in I$, then $t_0 + \delta' \in I$ for small $\delta' > 0$.

These properties imply $I = [\delta, r]$, so proof of $(*)$ is complete.
 This completes part 1.

Part 2 Geodesically complete \Rightarrow complete as a metric space.

Suppose $A \subset M$ is a bounded subset of diameter D with respect to dist_g . Then because any two points are joined by a minimizing geodesic we have

$$\text{for } p \in A, \quad A \subset \exp_p(\{v \in T_p M \mid \|v\| \leq D\})$$

Since $\{v \in T_p M \mid \|v\| \leq D\}$ is compact and \exp_p is continuous, A is contained in a compact set. Hence A is contained in the same compact set, and is therefore itself compact. So (M, dist_g) has the property that any bounded set has compact closure (which is stronger than completeness).

Part 3 Completeness \Rightarrow Geodesic completeness

Let $(p, v) \in TM$, $\|v\|=1$. Consider the path $\gamma(t) = \exp_p(tv)$
 This is defined on some interval $I \subset [0, \infty)$.

By fundamental existence theorem for geodesics, I is nonempty and open.
 We want to show it is also closed.

Let $b \in \bar{I}$ take $t_n \in I$ such that $t_n \rightarrow b$
 Since $\text{dist}(\gamma(t_n), \gamma(t_m)) = |t_m - t_n|$ for n, m large,

The sequence $\gamma(t_n)$ is Cauchy, and converges to $q \in M$.
 It is possible to show $q = \exp_p(bv)$, so $b \in I$. \square

