

Change of variables cont'd, Triple integrals

* Course instructor survey *

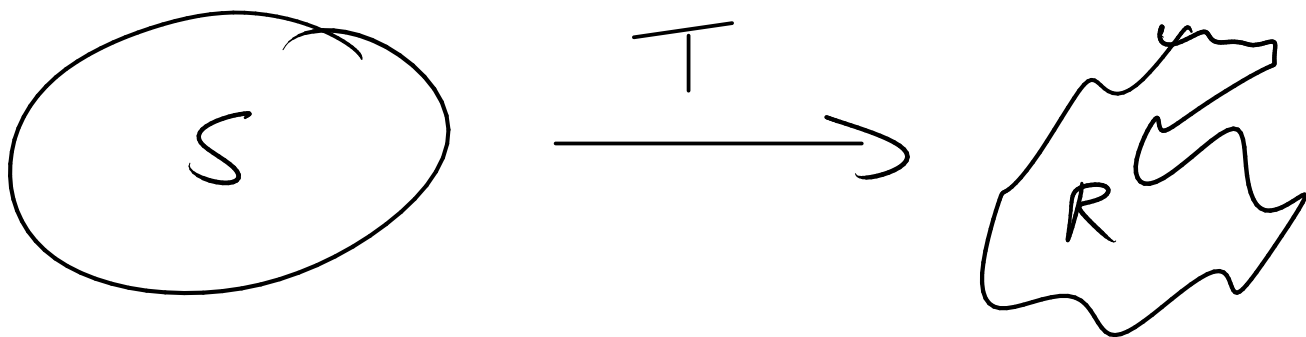
Justification for change of variables formula

$$\begin{cases} x = x(u, v) \\ y = y(u, v) \end{cases} \quad (x, y) = T(u, v) \text{ transformation}$$

$$\iint_R f(x, y) dA = \iint_S f(x(u, v), y(u, v)) \left| \frac{\partial(x, y)}{\partial(u, v)} \right| du dv$$

• R is the image of S under T

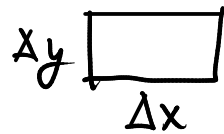
$$\frac{\partial(x, y)}{\partial(u, v)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial y}{\partial u} \\ \frac{\partial x}{\partial v} & \frac{\partial y}{\partial v} \end{vmatrix} \quad \text{Jacobian}$$



Q: Why is there the Jacobian factor?

in (x, y) coordinates $\iint f(x, y) dA$

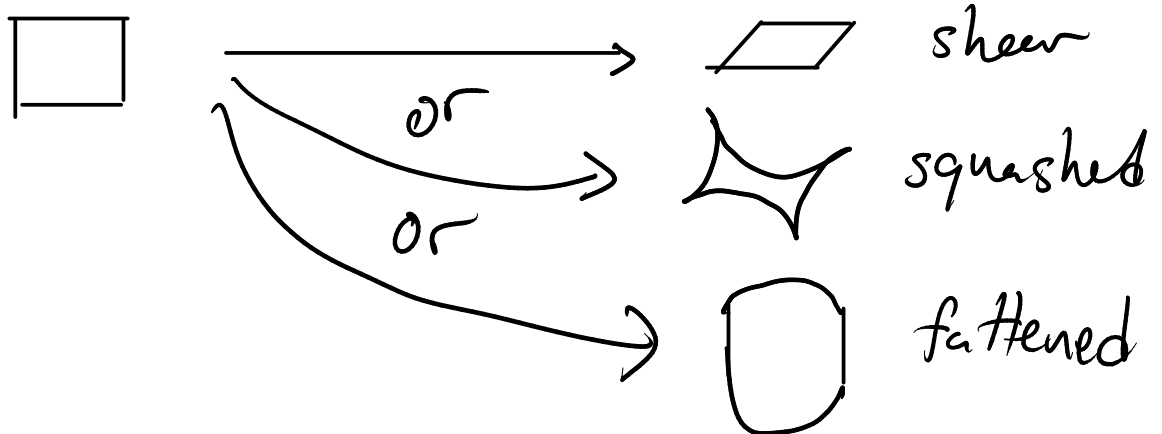
$$dA = dx dy$$



$$\Delta A = \Delta x \Delta y$$

Q: What happens to a small rectangle under Transformation T ?

$$(u, v) \xrightarrow{T} (x, y)$$



this means that the transformation T may distort areas.

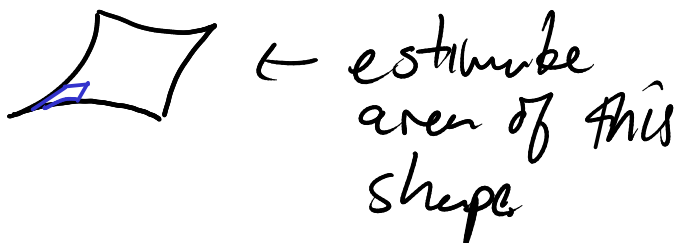
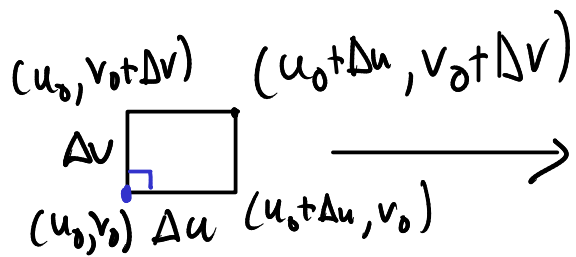
Areas don't match in the two coordinate systems.

$$\text{Area in } (u, v) = du dv \quad \text{Area in } (x, y) = dx dy$$

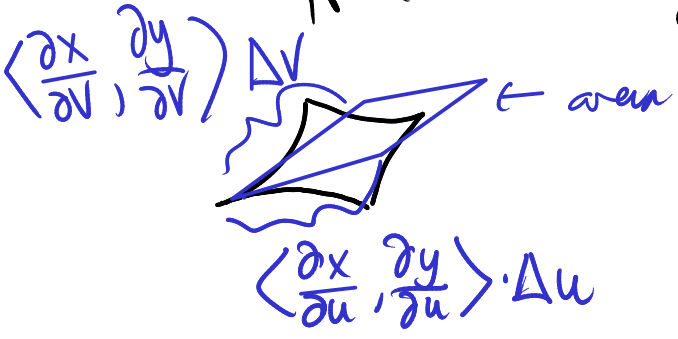
in general $du dv \neq dx dy$

Want: express (x, y) -area $dx dy$ in (u, v) coordinates

$$dA = dx dy = \left| \frac{\partial(x, y)}{\partial(u, v)} \right| du dv \quad \text{in fact.}$$



let's approximate by a parallelogram.



look at lower side $v = v_0$

$T(u, v_0)$ describes the lower side in (x, y) -coordinates

Approximate side as straight
 linear approximation on $T(u, v_0)$

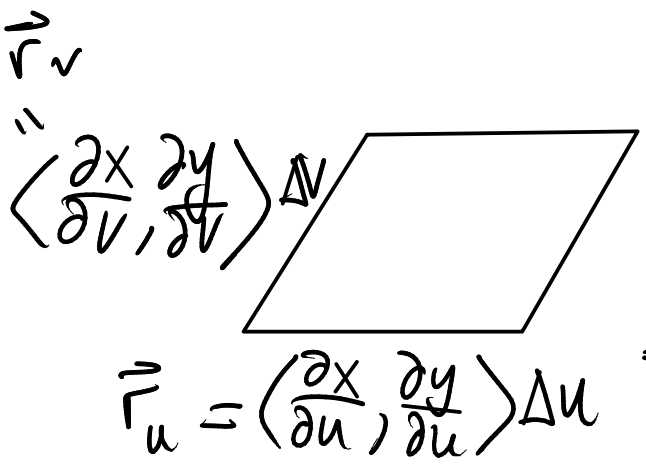
$$T(u, v_0) \approx T(u_0, v_0) + \frac{\partial T}{\partial u}(u_0, v_0) \Delta u$$

$$\left\langle \frac{\partial x}{\partial u}(u_0, v_0), \frac{\partial y}{\partial u}(u_0, v_0) \right\rangle$$

$T(u_0, v)$ describes the "left side".

$$T(u_0, v) \approx T(u_0, v_0) + \frac{\partial T}{\partial v}(u_0, v_0) \Delta v$$

$$\left\langle \frac{\partial x}{\partial v}(u_0, v_0), \frac{\partial y}{\partial v}(u_0, v_0) \right\rangle$$



$$\text{Area} = \left| \vec{r}_u \times \vec{r}_v \right|$$

$$= \left| \left\langle \frac{\partial x}{\partial u} \Delta u, \frac{\partial y}{\partial u} \Delta u, 0 \right\rangle \times \left\langle \frac{\partial x}{\partial v} \Delta v, \frac{\partial y}{\partial v} \Delta v, 0 \right\rangle \right|$$

$$\begin{aligned}
 \text{Area} &= |\vec{r}_u \times \vec{r}_v| = \left| \left\langle \frac{\partial x}{\partial u}, \frac{\partial y}{\partial u}, 0 \right\rangle \times \left\langle \frac{\partial x}{\partial v}, \frac{\partial y}{\partial v}, 0 \right\rangle \right| \Delta u \Delta v \\
 &= \left| \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial x}{\partial u} & \frac{\partial y}{\partial u} & 0 \\ \frac{\partial x}{\partial v} & \frac{\partial y}{\partial v} & 0 \end{vmatrix} \right| \Delta u \Delta v = \left| \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial y}{\partial u} \\ \frac{\partial x}{\partial v} & \frac{\partial y}{\partial v} \end{vmatrix} \vec{k} \right| \Delta u \Delta v \\
 &= \text{abs val} \left(\begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial y}{\partial u} \\ \frac{\partial x}{\partial v} & \frac{\partial y}{\partial v} \end{vmatrix} \right) \Delta u \Delta v \\
 &= \text{abs val} \left(\frac{\partial(x,y)}{\partial(u,v)} \right) \Delta u \Delta v
 \end{aligned}$$

in the limit as $\Delta u, \Delta v \rightarrow 0$, the approximation by the parallelogram becomes better,

$$dx dy = \text{abs. val.} \left(\frac{\partial(x,y)}{\partial(u,v)} \right) du dv$$

$$dx dy = \left| \frac{\partial(x,y)}{\partial(u,v)} \right| du dv$$

$|\text{Jacobian}| = \left| \frac{\partial(x,y)}{\partial(u,v)} \right|$ measures infinitesimal distortion of areas.

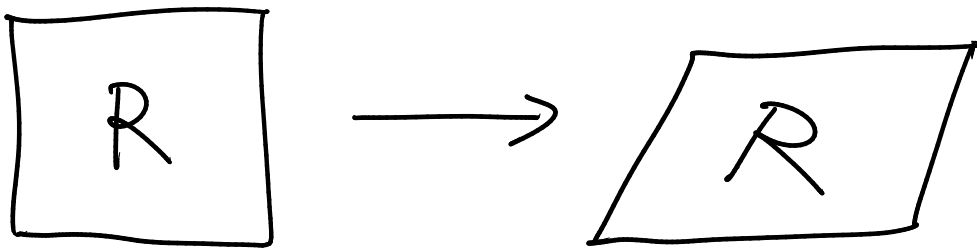
Why do we take absolute value of Jacobian?
Because Jacobian could be negative, and we don't want negative areas.

$$\frac{\partial x}{\partial u} \frac{\partial y}{\partial v} - \frac{\partial x}{\partial v} \frac{\partial y}{\partial u} < 0$$

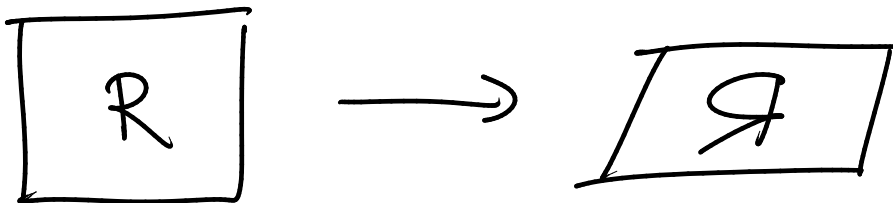
$$\left| \frac{\partial(x,y)}{\partial(u,v)} \right| = 1 \quad \text{area is preserved.}$$

$$dx dy = \left| \frac{\partial(x,y)}{\partial(u,v)} \right| du dv$$

Jacobian > 0 orientation preserving



Jacobian < 0 orientation reversing

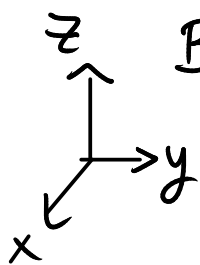


Examp $x = u$
 $y = -v$

$$\frac{\partial(x,y)}{\partial(u,v)} = \begin{vmatrix} 1 & 0 \\ 0 & -1 \end{vmatrix} = -1$$

Triple integrals $\iiint_E f(x,y,z) dV$

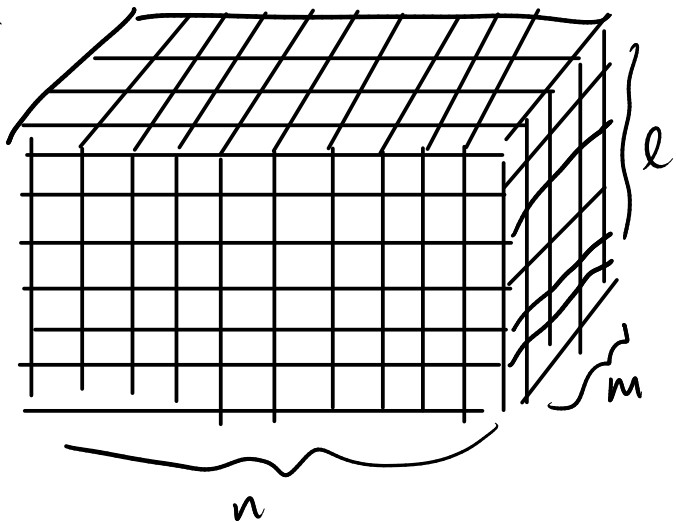
$E = 3d$ region $dV = dx dy dz$



$B =$ Rectangular Box

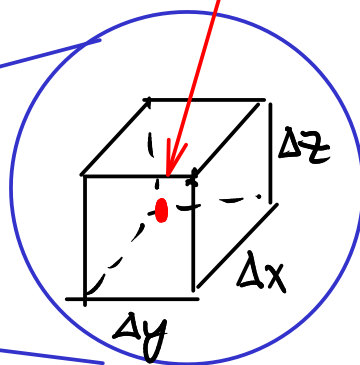
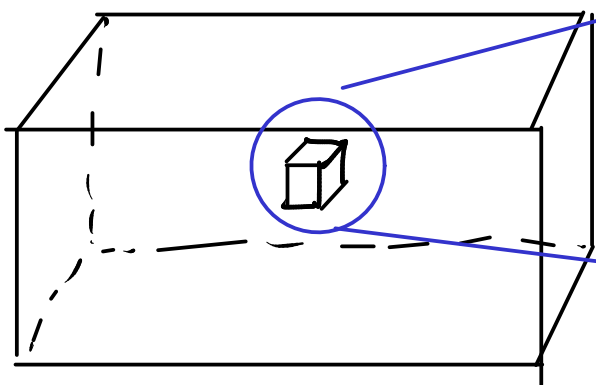
$$B = \{a \leq x \leq b, c \leq y \leq d, r \leq z \leq s\}$$

$$= [a, b] \times [c, d] \times [r, s]$$



$$\iiint_B f(x,y,z) dV$$

$$(x_{ijk}^*, y_{ijk}^*, z_{ijk}^*)$$



$$\Delta V = \Delta x \Delta y \Delta z$$

Riemann sum

$$\iiint_B f(x,y,z) dV \approx \sum_{i=1}^m \sum_{j=1}^n \sum_{k=1}^l f(x_{ijk}^*, y_{ijk}^*, z_{ijk}^*) \Delta V$$

To get true value of integral: Take limit $n, m, l \rightarrow \infty$
 $\Delta x, \Delta y, \Delta z \rightarrow 0$

can do this as iterated integral

$$\iiint_B f(x,y,z) dV = \int_r^s \int_c^d \int_a^b f(x,y,z) \underline{dx} \underline{dy} \underline{dz}$$

$$B = \{ a \leq x \leq b, c \leq y \leq d, r \leq z \leq s \}$$

Read integrals from inside \rightarrow out

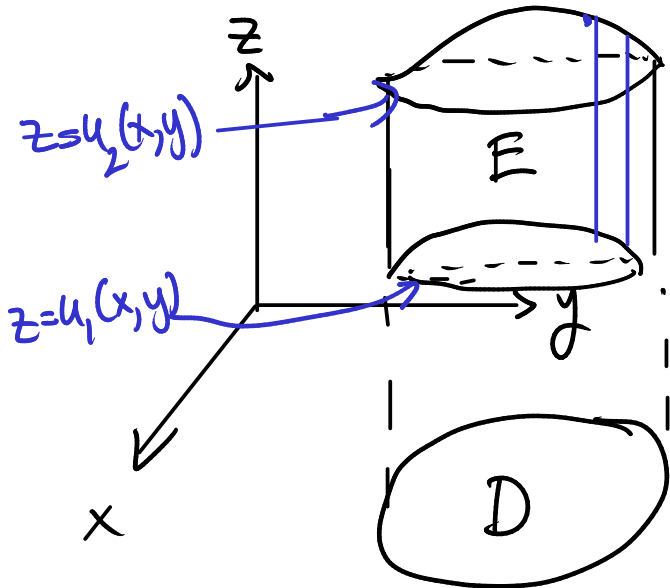
There are 6 possible orders

$$\begin{array}{ccc} dx dy dz & dy dx dz & dz dx dy \\ dx dz dy & dy dz dx & dz dy dx \end{array}$$

$$\begin{aligned} \int_0^1 \int_0^1 \int_0^1 xyz^2 dx dy dz &= \int_0^1 \int_0^1 \left[\frac{x^2}{2} yz^2 \right]_{x=0}^1 dy dz \\ &= \int_0^1 \int_0^1 \frac{1}{2} yz^2 dy dz = \int_0^1 \left[\frac{1}{2} \frac{y^2}{2} z^2 \right]_{y=0}^1 dz = \int_0^1 \frac{1}{2} \cdot \frac{1}{2} z^2 dz \\ &= \frac{1}{4} \left[\frac{z^3}{3} \right]_0^1 = \frac{1}{4} \cdot \frac{1}{3} = \frac{1}{12} \end{aligned}$$

More general region: Type 1 in 3d

Bounded by two graphs of functions of (x, y) .



3d region E sits over a 2d-region D in the (x, y) -plane

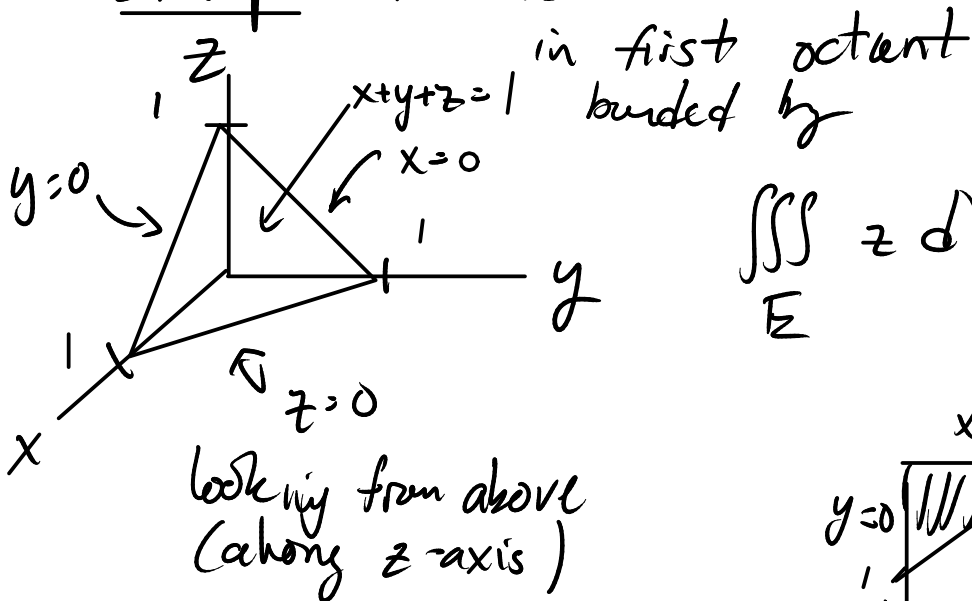
Bounded by 2 graphs

Integrate with respect to z first. then integrate over D.

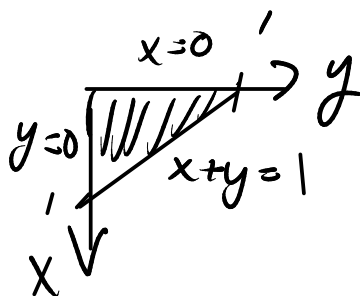
$$\iiint_E f(x, y, z) dV = \iint_D \left[\int_{u_1(x, y)}^{u_2(x, y)} f(x, y, z) dz \right] dA$$

then deal with integral over D as usual.

Example E = tetrahedron

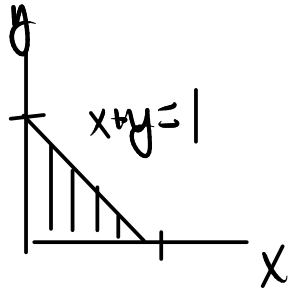


$$\iiint_E z dV$$



Bottom $z=0$ Top = slanted face $z=1-x-y$

$$\iiint_E z \, dV = \iint_D \left[\int_0^{1-x-y} z \, dz \right] dA$$



$$\iint_D [] \, dA = \int_0^1 \int_0^{1-x} [] \, dy \, dx$$

$$\iiint_E z \, dV = \int_0^1 \int_0^{1-x} \int_0^{1-x-y} z \, dz \, dy \, dx$$

$$= \int_0^1 \int_0^{1-x} \left[\frac{z^2}{2} \right]_0^{1-x-y} dy \, dx = \int_0^1 \int_0^{1-x} \frac{(1-x-y)^2}{2} dy \, dx$$

$$= \int_0^1 \left[-\frac{(1-x-y)^3}{6} \right]_0^{1-x} dx = \int_0^1 +\frac{1}{6} (1-x)^3 dx$$

$$= \left[-\frac{1}{24} (1-x)^4 \right]_0^1 = +\frac{1}{24}$$