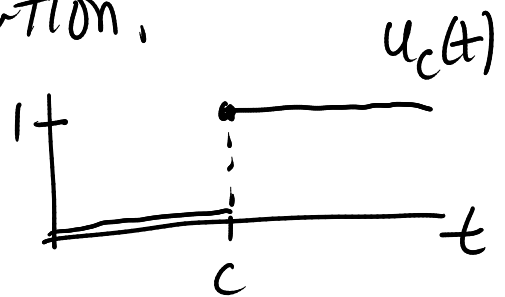
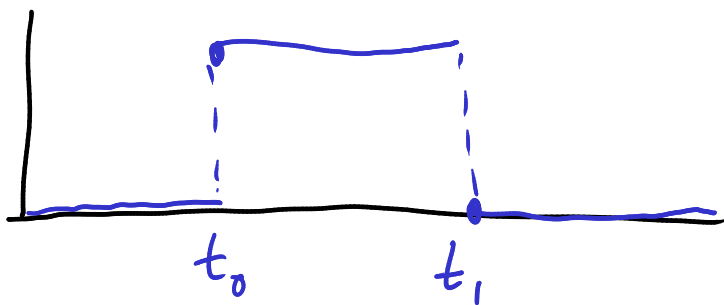


Impulse Functions & Convolution.

Last time: step functions



Using $u_c(t)$, can look at forcing functions that turn ON and OFF.



$$g(t) = u_{t_0}(t) - u_{t_1}(t)$$

$$mu'' + \gamma u' = mg + F(t)$$

An impulse means the force is applied instantaneously

If $g(t)$ is any forcing function then the impulse of $g(t)$ is

$$I = \int_{-\infty}^{\infty} g(t) dt = \int_{t_0}^{t_1} g(t) dt$$

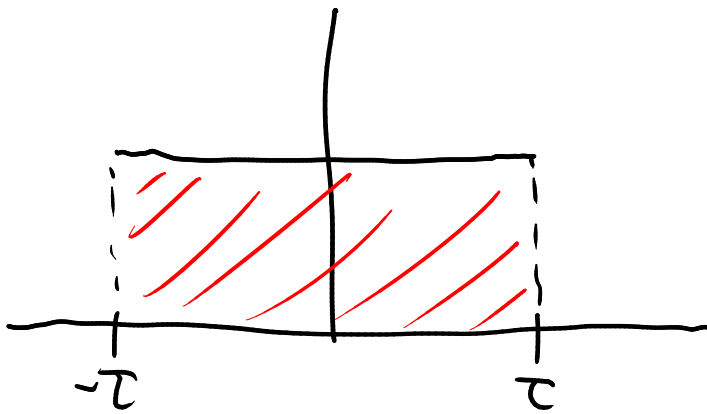
↑ if $g(t) = 0$ for $t < t_0$
 $t > t_1$

2nd law $F = \frac{dp}{dt}$

$$I = \Delta(\text{momentum})$$

Want to consider the limit where the impulse = change in momentum is fixed, but the time interval over which the force is applied goes to 0.

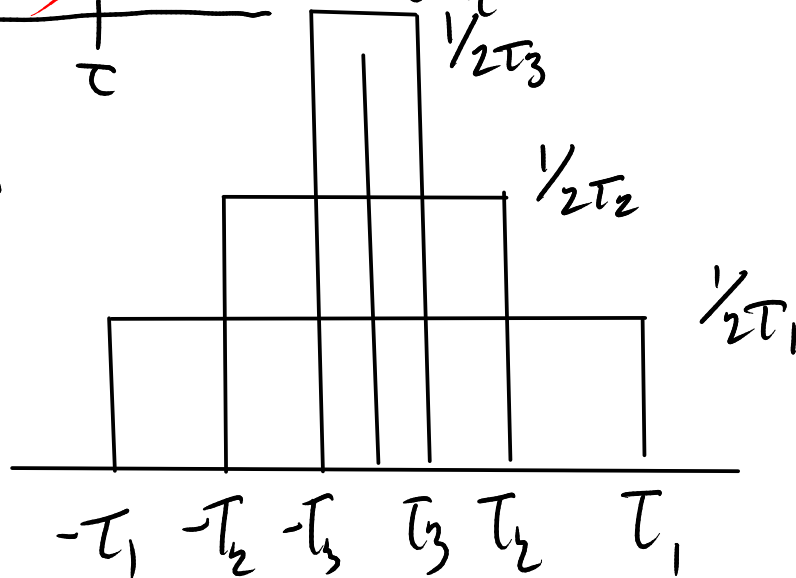
$$d_{\tau}(t) = \begin{cases} 1/2\tau & -\tau < t < \tau \\ 0 & \text{otherwise} \end{cases}$$



$$I = \int_{-\tau}^{\tau} d_{\tau}(t) dt$$

$$= \int_{-\tau}^{\tau} \frac{1}{2\tau} dt = \frac{1}{2\tau} 2\tau = 1$$

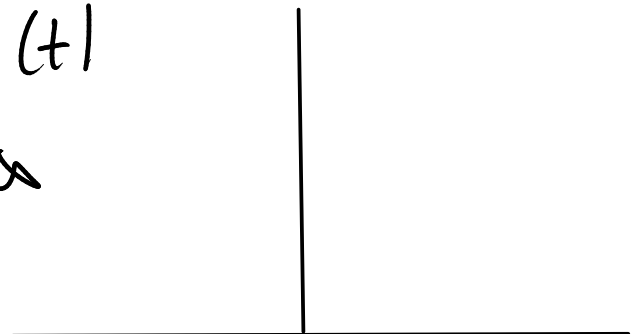
As $\tau \rightarrow 0$:



"Definition"

$$\delta(t) = \lim_{\tau \rightarrow 0} d_{\tau}(t)$$

Graph is "rectangle with height ∞ and width zero"



Properties: $\delta(t) = 0$ unless $t=0$

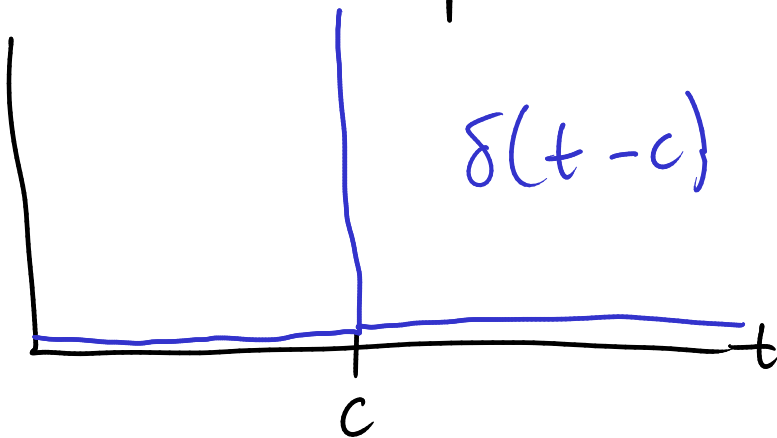
$$\int_{-\infty}^{\infty} \delta(t) dt = 1$$

Thinking of $\delta(t)$ as a function is a useful fiction
(strictly speaking $\delta(t)$ is a "distribution" or "generalized function")

Called Dirac Delta Function or unit impulse function

In physical terms it represents a unit impulse
delivered instantaneously.

We can have the impulse "hit" at time $t=c$



KEY PROPERTY of $\delta(t-c)$ is

if $f(t)$ is a continuous function

$$\text{then } \int_{-\infty}^{\infty} \delta(t-c) f(t) dt = f(c)$$

"Proof"

$$\int_{-\infty}^{\infty} \delta(t-c) f(t) dt = \lim_{\tau \rightarrow 0} \int_{-\infty}^{\infty} d_{\tau}(t-c) f(t) dt$$

$$= \lim_{\tau \rightarrow 0} \frac{1}{2\tau} \int_{c-\tau}^{c+\tau} f(t) dt \underset{\text{FTC}}{\approx} \frac{1}{2\tau} 2\tau f(c) = f(c)$$

$$\mathcal{L}\{\delta(t-c)\} = \int_0^{\infty} \delta(t-c) e^{-st} dt = e^{-sc}$$

$c > 0$

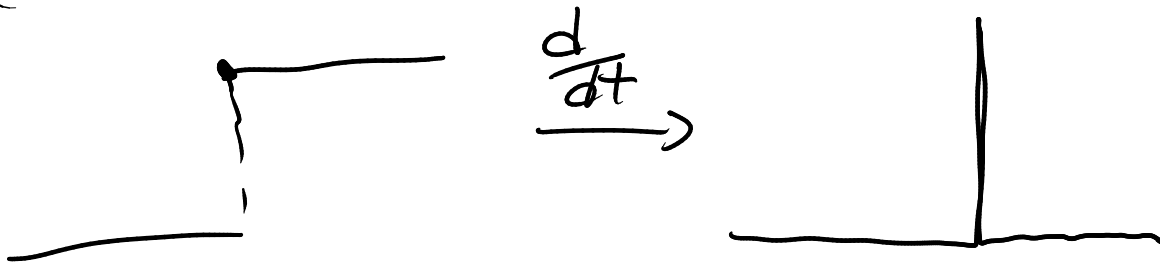
$$\text{If } c=0 : \mathcal{L}\{\delta(t)\} = 1$$

$$\text{Compare } \mathcal{L}\{u_c(t)\} = \frac{e^{-cs}}{s}$$

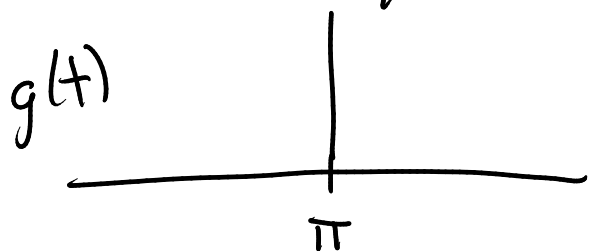
$$\text{Note } \mathcal{L}\{\delta(t-c)\} = s \mathcal{L}\{u_c(t)\}$$

$$\delta(t-c) = \frac{d}{dt} (u_c(t))$$

(strictly $u_c(t)$ isn't differentiable at c and $\delta(t-c)$ isn't even our honest function)



Solve $y'' + 4y = \delta(t - \pi)$ $y(0) = 0$, $y'(0) = 0$



$$Y(s) = \mathcal{L}\{y(t)\}$$

$$\begin{aligned} \mathcal{L}\{y''(t)\} &= s^2 Y(s) - sy(0) - y'(0) \\ &= s^2 Y(s) \end{aligned}$$

$$\mathcal{L}\{\delta(t - \pi)\} = e^{-\pi s}$$

$$y'' + 4y = \delta(t - \pi)$$

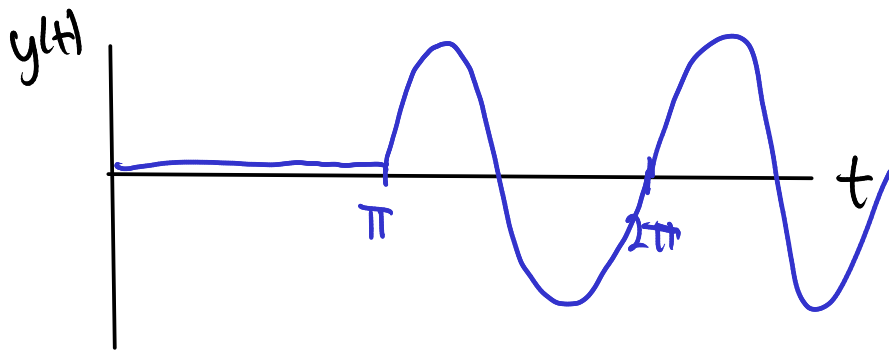
$$s^2 Y(s) + 4Y(s) = e^{-\pi s} \longrightarrow Y(s) = e^{-\pi s} \frac{1}{s^2 + 4}$$

Recall : $\mathcal{L}\{u_c(t) f(t - c)\} = e^{-cs} F(s)$

$$Y(s) = e^{-\pi s} \frac{1}{s^2 + 4} = e^{-\pi s} H(s) \text{ where } H(s) = \frac{1}{s^2 + 4}$$

$$h(t) = \mathcal{L}^{-1}\left\{\frac{1}{s^2 + 4}\right\} = \frac{1}{2} \mathcal{L}^{-1}\left\{\frac{2}{s^2 + 4}\right\} = \frac{1}{2} \sin 2t$$

$$\begin{aligned} y(t) &= u_{\pi}(t) h(t - \pi) = u_{\pi}(t) \cdot \frac{1}{2} \cdot \sin[2(t - \pi)] \\ &= u_{\pi}(t) \cdot \frac{1}{2} \cdot \sin(2t) \end{aligned}$$



Kick it and
it starts
working.

Convolution: what is $\mathcal{L}^{-1}\{F(s)G(s)\}$

eg. $\frac{1}{s} \cdot \frac{1}{(s^2+4)}$ or $e^{-5s} \frac{1}{s^2+2s+2}$ etc.

$\mathcal{L}\{f(t)g(t)\} = F(s)G(s)$ very wrong.

Q can we find $h(t)$ in terms of $f(t)$ and $g(t)$

so that $\mathcal{L}\{h(t)\} = F(s)G(s) = \mathcal{L}\{f(t)\} \cdot \mathcal{L}\{g(t)\}$

$$h(t) = \int_0^t f(t-\tau)g(\tau) d\tau = (f * g)(t)$$

is called the convolution of f and g .

To proof

$$F(s)G(s) = \left(\int_0^\infty f(t)e^{-st} dt \right) \left(\int_0^\infty g(t)e^{-st} dt \right)$$

→ combine these into a double integral,
and do a change of variables to get

$$\int_0^\infty \left(\int_0^t f(t-\tau)g(\tau) d\tau \right) e^{-st} dt$$

Can use this as alternative to partial fractions

$$H(s) = \frac{1}{s^2(s-5)} = \frac{1}{s^2} \cdot \frac{1}{s-5}$$

\parallel \parallel
 $F(s)$ $G(s)$

$$f(t) = t \quad g(t) = e^{5t}$$

$$h(t) = \mathcal{L}^{-1}(H(s)) = \int_0^t f(t-\tau)g(\tau) d\tau$$

$$= \int_0^t (t-\tau) e^{5\tau} d\tau$$

$$= t \int_0^t e^{5\tau} d\tau - \int_0^t \tau e^{5\tau} d\tau = \frac{1}{25} e^{5t} - \frac{t}{5} - \frac{6}{25}$$

Nice thing: get formula for $y(t)$ in terms of $g(t)$

$$y'' + 4y = g(t) \quad g(t) \text{ any forcing function.}$$

$$y(0) = 1 \quad y'(0) = 2$$

$$\mathcal{L}\{y''(t)\} = s^2 Y(s) - sy(0) - y'(0) = s^2 Y(s) - s - 2$$

$$s^2 Y(s) - s - 2 + 4Y(s) = G(s) \quad G(s) = \mathcal{L}\{g(t)\}$$

$$(s^2 + 4) Y(s) = s + 2 + G(s)$$

$$Y(s) = \frac{s+2}{s^2+4} + \frac{G(s)}{s^2+4}$$

Inverse \mathcal{L}^{-1} : $\frac{s+2}{s^2+4} = \frac{s}{s^2+4} + \frac{2}{s^2+4} \leftrightarrow \cos 2t + \sin 2t$

$$\frac{G(s)}{s^2+4} = G(s)H(s), \quad H(s) = \frac{1}{s^2+4}$$

$$h(t) = \frac{1}{2} \sin 2t$$

$$\mathcal{L}^{-1}\{H(s)G(s)\} = \int_0^t h(t-\tau) g(\tau) d\tau$$

$$= \int_0^t \frac{1}{2} \sin[2(t-\tau)] g(\tau) d\tau$$

Full solⁿ: $y(t) = \underbrace{\cos 2t + \sin 2t}_{\text{solns of homog eqn}} + \underbrace{\int_0^t \frac{1}{2} \sin[2(t-\tau)] g(\tau) d\tau}_{\text{integral transformation of the forcing function.}}$

Fact: $f * g = g * f$

$$\int_0^t f(t-\tau) g(\tau) d\tau = \int_0^t f(\tau) g(t-\tau) d\tau$$

$$ay'' + by' + cy = g(t) \quad y(0) = y_0 \quad y'(0) = y'_0$$

$$(as^2 + bs + c)Y(s) - (ast + b)y_0 - ay'_0 = G(s)$$

$$Y(s) = \frac{1}{as^2 + bs + c} \left((ast + b)y_0 + ay'_0 + G(s) \right)$$

$H(s) = \frac{1}{as^2 + bs + c}$ is called the transfer function of the differential equation.

$h(t) = \mathcal{L}^{-1}\{H(s)\}$ is called the impulse response.

Fact about $h(t)$:

$h(t)$ solves the equation $ay'' + by' + cy = \delta(t)$
 $y_0 = 0 \quad y'_0 = 0$