

Parametric Equations

describe \emptyset curves in the xy -plane
 not as $y = f(x)$, but by writing
 x and y as functions of yet another
 variable t .

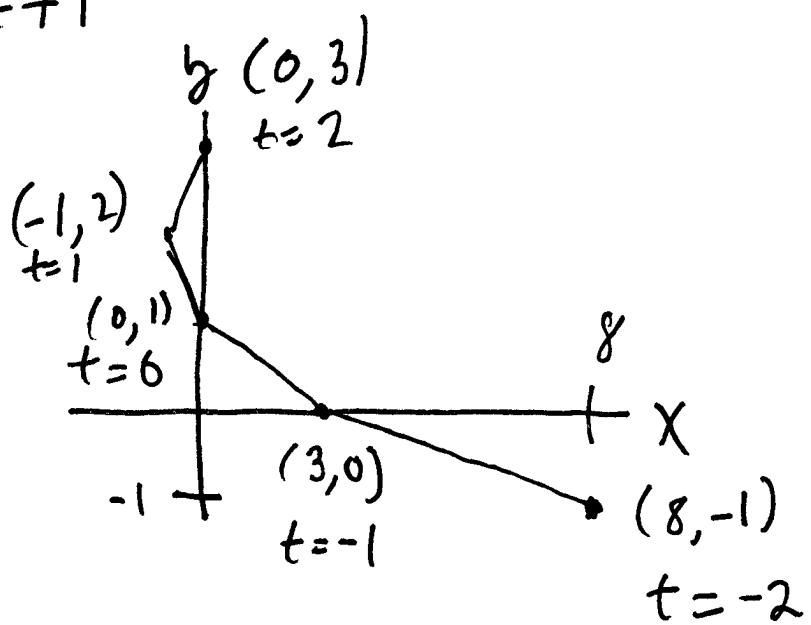
t - parameter "time"

$$\begin{cases} x = f(t) \\ y = g(t) \end{cases}$$

$(x, y) = (f(t), g(t))$
 $(x, y) = (x(t), y(t))$

Example $\begin{cases} x(t) = t^2 - 2t \\ y(t) = t + 1 \end{cases}$

t	x	y
-2	8	-1
-1	3	0
0	0	1
1	-1	2
2	0	3



As t runs through different values,
 $(x(t), y(t))$ traces out a curve in the plane.

In this case, the curve is sideways parabola.

We can "eliminate the parameter"
to get the "Cartesian equation" of
the curve.

$$x = t^2 - 2t$$

$$y = t + 1 \Rightarrow t = y - 1$$

$$x = (y-1)^2 - 2(y-1) \quad \text{"eliminating the parameter"}$$

$$x = y^2 - 2y + 1 - 2y + 2 = y^2 - 4y + 3$$

$$x = y^2 - 4y + 3 \quad \text{equation for Parabola}$$

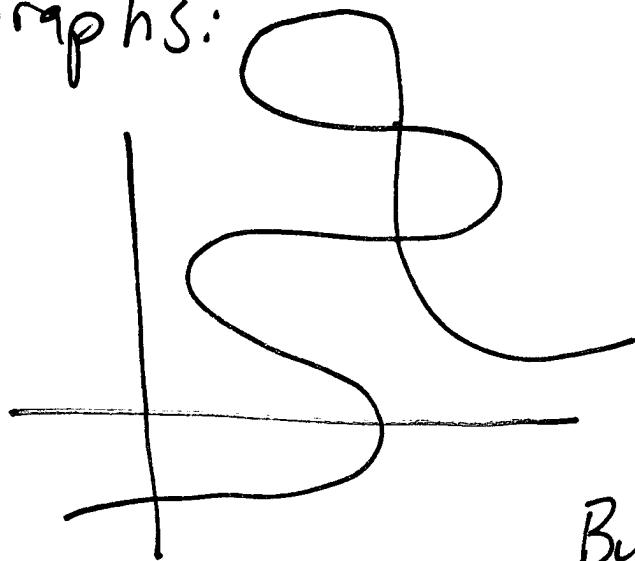
The Cartesian equation contains less information³ than the parametric equations.

The parametric equations attach a "time" / value of t to each point on the curve.

They tell us "when" the "particle"
~~walk~~ was at a particular location.

At time t , at $(x(t), y(t))$
In physics, they describe the trajectory
of a particle.

ASIDE: parametric equations let you write formulas for curves that are not graphs: ⁴



Cannot be
the graph of
a function

But it does have a
parametric description.

self-intersection

\Leftrightarrow two values of t where
 (x, y) are equal

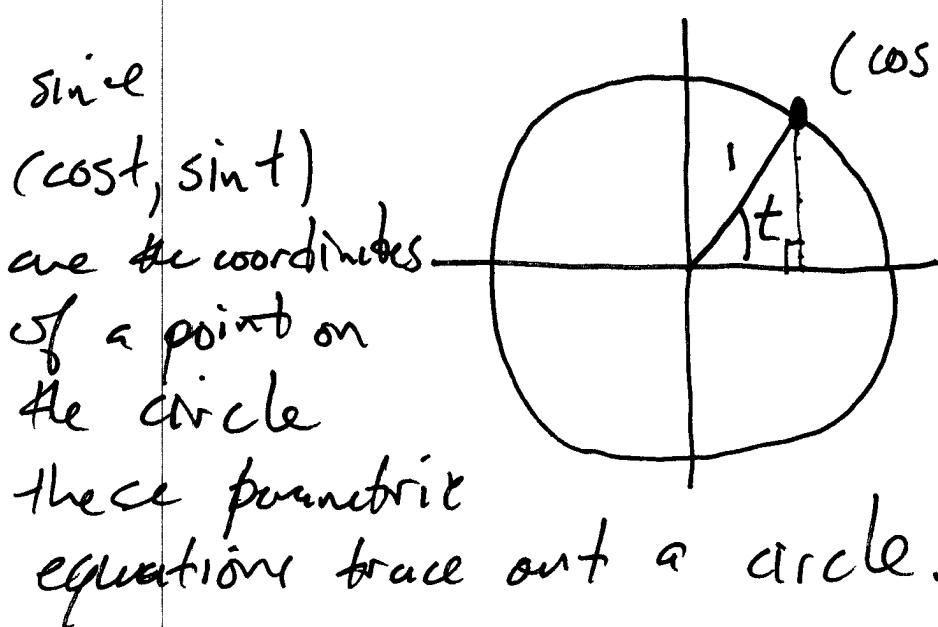
t_1, t_2 such that $\begin{cases} x(t_1) = x(t_2) \\ y(t_1) = y(t_2) \end{cases}$

Example everyone should know:

Parametric equations for a circle

a.k.a. "Uniform circular motion"

$$\begin{cases} x(t) = \cos t \\ y(t) = \sin t \end{cases} \quad \text{for } 0 \leq t \leq 2\pi$$

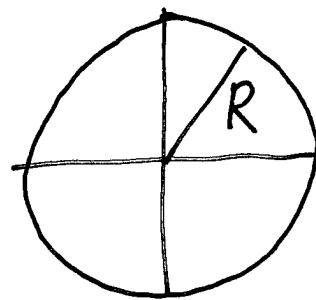


Pythagorean Identity $\cos^2 t + \sin^2 t = 1$

Cartesian equation $\rightarrow x^2 + y^2 = 1$
for a circle

What if we want the Radius to be R ?⁶

$$\left\{ \begin{array}{l} x(t) = R \cos t \\ y(t) = R \sin t \end{array} \right.$$

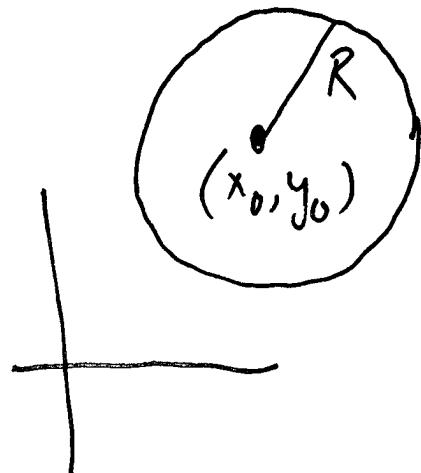


$$x^2 + y^2 = R^2$$

What if I want the center to be at (x_0, y_0)

just add it in:

$$\left\{ \begin{array}{l} x(t) = R \cos t + x_0 \\ y(t) = R \sin t + y_0 \end{array} \right.$$



$$(x - x_0)^2 + (y - y_0)^2 = R^2$$

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One more thing to fiddle with: ~~now~~
"The parameterization".

Can parameterize the same curve in different ways

$$\begin{cases} x = \cos t \\ y = \sin t \end{cases}$$

As t goes from 0 to 2π ,
these parametric equations
trace out the circle once.

What if I want the circle to be traced
once as t goes from 0 to T ?

Replace t by $\frac{2\pi}{T}t$.

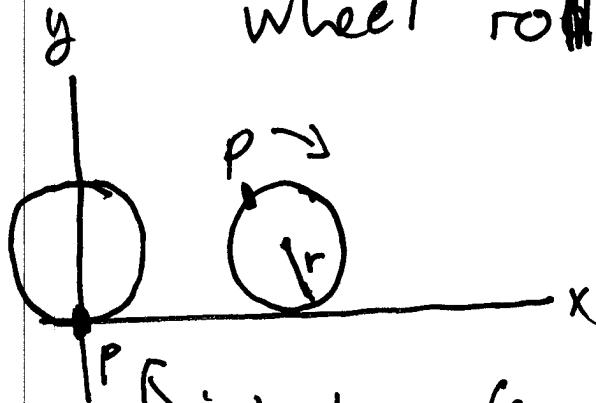
$$\begin{cases} x = \cos\left(\frac{2\pi}{T}t\right) \\ y = \sin\left(\frac{2\pi}{T}t\right) \end{cases} \quad 0 \leq t \leq T$$

T = period

$1/T$ = frequency

$2\pi/T$ = angular
frequency

Cycloid = curve traced out by a point P on the rim of a wheel as the wheel rolls.

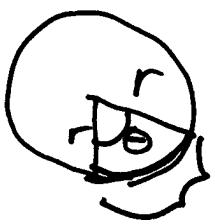


initial configuration.

Parameter = θ = the angle through which the wheel has rotated since the initial configuration.

Step 1: figure out how the center of the wheel moves.

After rotation through angle θ , the wheel rolls to the right a distance $r\theta$.



$$\text{distance} = r\theta$$

$$\left\{ \begin{array}{l} x_{center} = r\theta \\ y_{center} = r \end{array} \right.$$

Step 2 How does the point on the rim move relative to the center?

It rotates clockwise from its initial position at the bottom.

$$r \cos\left(-\frac{\pi}{2} - \theta\right)$$

why $-\frac{\pi}{2} - \theta$?

$$r \sin\left(-\frac{\pi}{2} - \theta\right)$$

starts at the bottom
 \Rightarrow when $\theta = 0$,

P makes an angle $-\frac{\pi}{2}$
 with the horizontal
 rotates clockwise add $-\theta$.

Add them

$$\left\{ \begin{array}{l} x(t) = r \cos\left(-\frac{\pi}{2} - \theta\right) + r\theta \end{array} \right.$$

$$\left\{ \begin{array}{l} y(t) = r \sin\left(-\frac{\pi}{2} - \theta\right) + r \end{array} \right.$$

$$\left\{ \begin{array}{l} x(t) = r(-\sin\theta) + r\theta = r(\theta - \sin\theta) \end{array} \right.$$

$$\left\{ \begin{array}{l} y(t) = r(-\cos\theta) + r = r(1 - \cos\theta) \end{array} \right.$$